



***HULL AND MOTION MONITORING SYSTEMS  
FOR THE FRENCH NAVY AMPHIBIOUS SHIPS***

***«MISTRAL» AND «TONNERRE»***



## ***System description – Main characteristics***

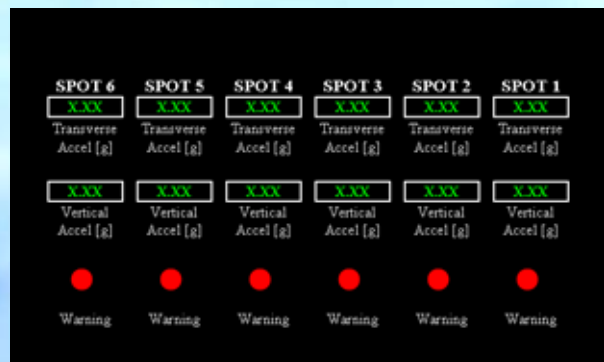
- Measurements and acquisition of data related to strains in the hull and to motions in various ship locations,
- Real time data processing to derive relevant criteria for the ship navigation and helicopter operations,
- Display on Navigation and Avia bridges of corresponding relevant criteria,
- Storage of raw and processed data for post-processing,
- System based on existing HULLMOS<sup>®</sup> system and adapted to the ship operations specificities,

## ***System Description – Main components***

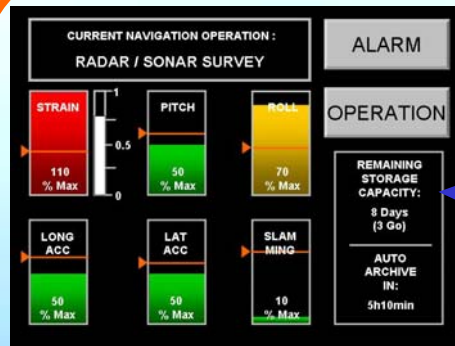
- Central unit : HULLMOS LAN management, data processing and storage, driving of NAV and AVIA MMI, interface with ship LAN (NAV1 for motions and WIND), Ethernet connection for external system,
- ARCNET LAN (cables and hubs) : power supply/configuration of sensors and data acquisition,
- Five strain sensors SBSG (Short Base Strain Gauge) : measurement of monodirectional strains in five ship locations around midship,
- Two vertical accelerometers at ship bow and stern,
- Motion data (motion, speed and accelerations at user defined ship points) derived from NAV1 data (heading, roll, pitch, heave, position, speed, UTC time),
- Two remote displays: on NAV bridge and on AVIA bridge
- Real time sea state estimation from recorded ship motion using SSE (Sea State Estimator) module; combination with bending moment transfer function for real time estimation of bending moment and comparison with strain measurements

# French Navy amphibious ships

## « Mistral » and « Tonnerre »



AVIA



NAV



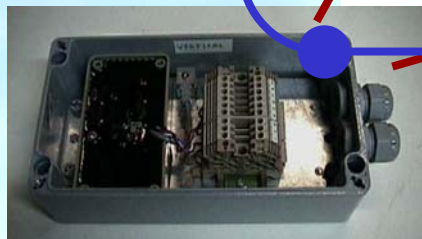
Ethernet



NAV1 (motions)

WIND

LAN



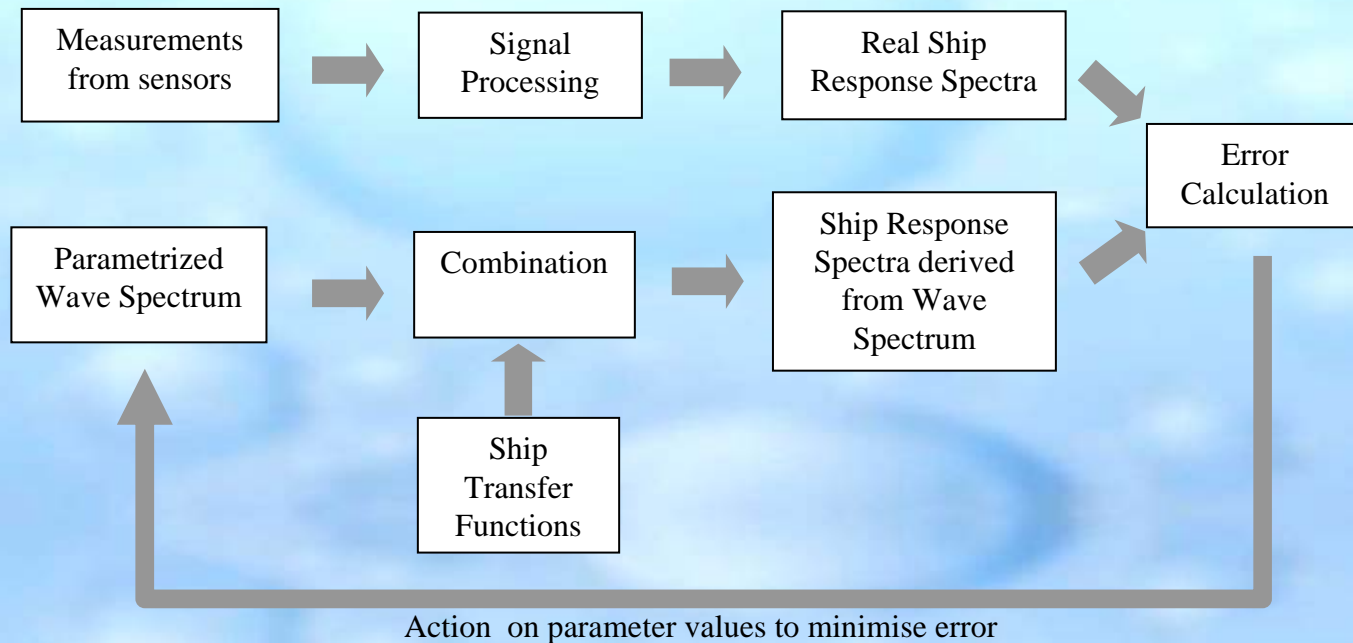
Vert. accelerometer



Strain gauge sensor

**Hull & motion monitoring system for NAV and AVIA operations**

## Principle



- Use of classical wave spectra with 3 to 5 parameters ( $H_s$ ,  $T_p$ , direction, frequency dispersion, incidence dispersion)
- Possibility to search for two superposed wave spectra
- Optimisation process adapted to the specificity of the present problem :
  - Local Search
  - Global Search

# Sea State Estimator

## MMI

